Section 4.5-4.6 Dimension and rank of vector spaces

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 $v \rightarrow (v)_{e} \in \mathbb{R}^{n}$

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Thm9 If a vector space V has a basis $B = \{b_1, b_2, \dots, b_n\}$, then any set in V containing more than *n* vectors must be linearly dependent. (i.e., a basis (amst have more than r vertex)

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 - The coordinate vectors [u₁]_B,..., [u_p]_B form a linearly dependent set in Rⁿ, because there are more vectors (p) than entries (n) in each vector.

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 - So there exist scalars c_1, c_2, \ldots, c_p , not all zero, such that

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• Since c_i are not all zero, $\{u_1, \ldots, u_p\}$ is linearly dependent.

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• Theorem 10: If a vector space V has a basis of n vectors, then every basis of V must consist of exactly n vectors.

$$B_1 - n$$
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 - Thus B₂ consists of exactly *n* vectors.

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 - 3-dimension: the R³.

Ex. Find the dimension of the subspace $H = \{ \begin{bmatrix} a - 3b + 6c \\ 5a + 4d \\ b - 2c - d \\ 5d + \end{bmatrix} : a, b, c, d \in \mathbf{R} \}.$

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Sol: Each vector in H can be written as a linear combination

$$\begin{bmatrix} a - 3b + 6c \\ 5a + 4d \\ b - 2c - d \\ 5d \end{bmatrix} = a \begin{bmatrix} 1 \\ 5 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} -3 \\ 0 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 6 \\ 0 \\ -2 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 4 \\ -1 \\ 5 \end{bmatrix} = av_1 + bv_2 + cv_3 + bv_2 + cv_3 + bv_3 + bv_4 + bv_$$

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So $H = Span\{v_1, v_2, v_3, v_4\}$.

By observation or by looking at the reduced echelon of the matrix $\begin{bmatrix} v_1 & v_2 & v_3 & v_4 \end{bmatrix}$, we see that v_1, v_2, v_4 form a basis for *H*.

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By observation or by looking at the reduced echelon of the matrix $\begin{bmatrix} v_1 & v_2 & v_3 & v_4 \end{bmatrix}$, we see that v_1, v_2, v_4 form a basis for H. So dimH = 3.

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 - If S spans H, then S is a basis for H.
 - Otherwise, there is some v_{k+1} in H that is not in Span S. But then {v₁, v₂,..., v_k, v_{k+1}} is linearly independent, because no vector in the set can be a linear combination of vectors that precede it.

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 - We can continue the process of expanding S to a larger linearly independent set in H.
 - As the number of elements in S cannot never exceed the dimension of V, the process will stop, that is, at some stage, S will span H, and we obtain a basis.
 - $dim H \leq dim V$ follows as a corollary.

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- Any set of exactly p elements that span V is automatically a basis for V.
- Pf. Let S be a set of linearly independent set of p elements. Then by Theorem 11, S can be extended to a basis, which contains p elements. So S itself must be a basis.
 - Now suppose S has p elements and span V. Then by the Spanning Set Theorem, S contains a basis. But a basis contains p elements, so S must be a basis.

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The dimension of *Nul* A is the number of free variables in the equation Ax = 0, and the dimension of *Col* A is the number of pivot columns in A.

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To see the dimension of *Nul A*, we suppose that Ax = 0 has k free variables. Then each solution to Ax = 0 can be expression a linear combination of k independent vectors, one for each free variable. So the k vectors form a basis for *Nul A*.

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Ex. Find the dimension of the null space and column space of

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

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Sol. Row reduce the augmented matrix [A 0] to echelon form:

$$\begin{bmatrix}
 1 & -2 & 2 & 3 & -1 & 0 \\
 0 & 0 & 1 & 2 & -2 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0
 \end{bmatrix}$$

$$\begin{aligned}
 f(col (Ai)) &= 2 \\
 dim(Nul (Hi)) &= 3
 \end{aligned}$$

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There are two pivot columns, so dim Col A = 2.

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• Theorem: Let A be an $m \times n$ matrix. Then rank $A + \dim Nul A = n$.

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It is indeed true....

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- Since the rows of A are the columns of A^T, we could also write Col A^T in place of Row A.
- One way to study *Row A* is to study *Col A^T*. But there are more directed ways to do it!

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• Theorem: If two matrices A and B are row equivalent, then their row spaces are the same. If B is in echelon form, the nonzero rows of B form a basis for the row space of A as well as for that of B.

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On the other hand, the row operations are reversible, so the same argument shows that the row space of A is contained in the row space of B. So the two row spaces are the same.

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- Theorem: If two matrices A and B are row equivalent, then their row spaces are the same. If B is in echelon form, the nonzero rows of B form a basis for the row space of A as well as for that of B.
- Pf. If B is obtained from A by row operations, the rows of B are linear combinations of the rows of A.

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Ex. Find bases for the row space, column space, and the null space of the matrix

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix}$$

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Sol. We first row reduce A to B (echelon form):

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By the theorem, the basis for row space of A is the first three rows of B: {(1,3,-5,1,5), (0,1,-2,2,-7), (0,0,0,-4,20)}.

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• The pivot columns of *B* (thus *A*) are the the first, second and fourth columns. So a basis for column space of *A* is the first, second, and fourth columns of *A*:

$$\{(-2, -5, 8, 0, -17)^T, (1, 3, -5, 1, 5)^T, (1, 7, -13, 5, -3)^T\}.$$

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• To find a basis for null space of A, we write the solution set of Ax = 0 in terms of free variables (x_3 and x_5): $x_1 = -x_3 - x_5, x_2 = 2x_3 - 3x_5, x_4 = 5x_3.$ $X = \begin{pmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \\ X_7 \end{pmatrix} = \begin{pmatrix} -X_7 - X_5 \\ z \times y - 3 \times s \\ s \times y \\ S \times s \\ K_7 \end{pmatrix} = \begin{pmatrix} -X_7 \\ 2 \times y \\ s \times y \\ S \times s \\ K_7 \end{pmatrix} = \begin{pmatrix} -X_7 \\ -X_5 \\ -3 \times s \\ 0 \\ K_7 \end{pmatrix} = X_3 \begin{pmatrix} -1 \\ 2 \\ 1 \\ s \\ 0 \\ K_7 \end{pmatrix} + \chi_7 \begin{pmatrix} -1 \\ -3 \\ 0 \\ 0 \\ K_7 \end{pmatrix} = X_3 \begin{pmatrix} -1 \\ 2 \\ 1 \\ s \\ 0 \\ 1 \end{pmatrix}$ The pivot columns of B (thus A) are the first, second and fourth columns. So a basis for column space of A is the first, second, and fourth columns of A:

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• Therefore a basis for Nul A is $\{(-1, 2, 1, 0, 0)^T, (-1, -3, 0, 5, 1)^T\}$.

The Rank Theorem

• The Rank Theorem: The dimensions of the column space and the row space of an $m \times n$ matrix A are equal. Furthermore, rank $A + \dim Nul \ A = n$.

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 - Furthermore, *B* has a nonzero row for each pivot. And these nonzero rows form a basis for row space of *B* (thus *A*).

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 - Furthermore, *B* has a nonzero row for each pivot. And these nonzero rows form a basis for row space of *B* (thus *A*).
 - Thus the dimension of row space of A also equals the number of pivots in A, which equals the rank of A.
 - The second part follows from *rank* $A = \dim Row A = \dim Col A$ and *rank* $A + \dim Nul A = n$.

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Ex. (a) If A is a 7 × 9 matrix with a two-dimensional null space, what is the rank of A?
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Sol. (a) the rank of A is 9-2=7.

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- Sol. (a) the rank of A is 9 2 = 7.

(b) A 6×9 matrix cannot have a two-dimensional null space, for otherwise, the rank of A is 9 - 2 = 7, which equals the dimension of column space, but the column space is a subspace of \mathbf{R}^6 .

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Thm. (Invertible Matrix Theorem (continued)) let A be an $n \times n$ matrix. Then the following statements are each equivalent to the statement that A is an invertible matrix.

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