Section 6.2-6.3 Orthogonal sets and orthogonal projections

Gexin Yu gyu@wm.edu

College of William and Mary

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Theorem 4: If S = {u₁,..., u_p} is an orthogonal set of nonzero vectors in Rⁿ, then S is linearly independent and hence is a basis for the subspace spanned by S.

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because u_1 is orthogonal to u_2, \ldots, u_p .

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- Since u_1 is nonzero, $u_1 \cdot u_1$ is not zero and so $c_1 = 0$.
- Similarly, c_2, \ldots, c_p must be zero.
- Thus S is linearly independent.

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• An orthogonal basis for a subspace W of **R**ⁿ is a basis for W that is also an orthogonal set.

$$\begin{pmatrix} l \\ 0 \\ l \\ 0 \\ 0 \\ l \\ 0$$

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• Theorem 5: Let $\{u_1, \ldots, u_p\}$ be an orthogonal basis for a subspace W of \mathbb{R}^n . For each y in W, the weights in the linear combination $y = c_1 u_1 + \ldots + c_p u_p$ are given by $c_j = \frac{y \cdot u_j}{u_j \cdot u_j}$ for $j = 1, \ldots, p$.

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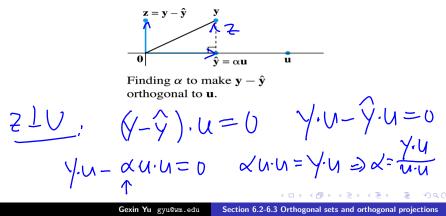
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• To find c_i , we can similarly compute $y \cdot u_i$ and solve for c_i .

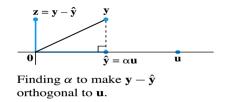
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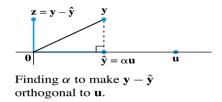
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Given any scalar α, let z = y − αu. Then y − ŷ is orthogonal to u if and only if 0 = (y − αu) · u = y · u − αu · u.

• That is, $y = \hat{y} + z$ with z orthogonal to u if and only if $\alpha = \frac{y \cdot u}{u \cdot u}$ and $\hat{y} = \frac{y \cdot u}{u \cdot u} u$.

• The vector \hat{y} is called the orthogonal projection of y onto u, and the vector z is called the component of y orthogonal to u.

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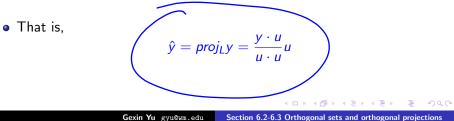
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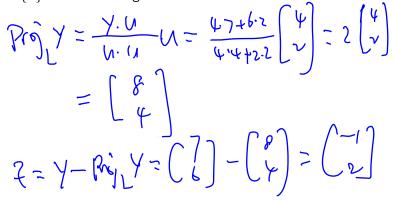
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 - That is, $[7 \ 6] = [8 \ 4] + [-1 \ 2]$.

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Orthonormal sets

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- If W is the subspace spanned by such a set, then {u₁,..., u_p} is an orthonormal basis for W, since the set is automatically linearly independent, by Theorem 4.

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- The simplest example of an orthonormal set is the standard basis $\{e_1, \ldots, e_n\}$ for \mathbb{R}^n .
- Any nonempty subset of $\{e_1, \cdots, e_n\}$ is orthonormal, too

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- The columns of U all have unit length if and only if $u_i^T u_i = 1$ for i = 1, 2, 3.

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Orthonormal columns of a matrix

- Theorem 6: an $n \times m$ matrix U has orthonormal columns if and only if $U^T U = I$.
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- The columns of U all have unit length if and only if $u_i^T u_i = 1$ for i = 1, 2, 3.
- From above conditions, the theorem follows immediately.

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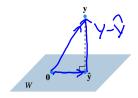
 The above properties say that the linear mapping x → Ux preserves lengths and orthogonality.

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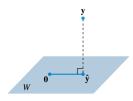
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- Given a vector y and a subspace W in Rⁿ, there is a vector ŷ in W such that (1) ŷ is the unique vector in W for which y − ŷ is orthogonal to W, and (2) ŷ is the unique vector in W closest to y.



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 These two properties of ŷ provide the key to finding the least-squares solutions of linear systems. • Theorem 8: Let W be a subspace of \mathbb{R}^n . Then each y in \mathbb{R}^n can be written uniquely in the form $y = \hat{y} + z$, where \hat{y} is in W and z is in W^{\perp} .

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- In fact, if $\{u_1, \dots, u_p\}$ is any orthogonal basis of W, then

$$\hat{y} = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \ldots + \frac{y \cdot u_p}{u_p \cdot u_p} u_p \text{ and } z = y - \hat{y}$$

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• To see that $z = y - \hat{y}$ is in W^{\perp} , we observe that z is orthogonal to each u_j in the basis for W, thus to every vector in W.

$$\begin{array}{c} \left(\begin{array}{c} z \perp U_{i} \\ y = C_{i}U_{i} + C_{i}U_{i} + \cdots + C_{i}U_{i} \end{array} \right) \cdot U_{i} = 0 \\ \hline \end{array} \\ \begin{array}{c} y = C_{i}U_{i} + C_{i}U_{i} + \cdots + C_{i}U_{i} \end{array} \\ \hline \end{array} \\ \begin{array}{c} y \cdot U_{i} = - \left(\begin{array}{c} U_{i} \cdot U_{i} \\ \end{array} \right) \\ \hline \end{array} \\ \hline \end{array} \\ \begin{array}{c} y \cdot U_{i} = - \left(\begin{array}{c} U_{i} \cdot U_{i} \\ \end{array} \right) \\ \hline \end{array} \\ \begin{array}{c} y \cdot U_{i} = - \left(\begin{array}{c} U_{i} \cdot U_{i} \\ \end{array} \right) \\ \hline \end{array} \\ \end{array} \\ \begin{array}{c} y \cdot U_{i} = - \left(\begin{array}{c} U_{i} \cdot U_{i} \\ \end{array} \right) \\ \hline \end{array} \\ \end{array}$$

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 - So vector $v = \hat{y} \hat{y_1}$ is in W, but also in W^{\perp} , as $z z_1$ is in W^{\perp} .
 - Hence $v \cdot v = 0$, and implies that v = 0. So $\hat{y} = \hat{y_1}$ and $z = z_1$.

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$$\hat{y} = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \frac{y \cdot u_2}{u_2 \cdot u_2} u_2 = \frac{q}{30} \begin{pmatrix} 2 \\ 5 \\ -1 \end{pmatrix} + \frac{3}{6} \begin{bmatrix} -2 \\ 1 \\ 1 \end{pmatrix}$$

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• And $z = y - \hat{y} = \begin{bmatrix} 7/5\\0\\14/5 \end{bmatrix}$

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 In this case, proj_Wy = y. In particular, if y is in W = Span{u₁,..., u_p}, then proj_Wy = y.

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• Theorem 9. Let W be a subspace of \mathbb{R}^n , let y be any vector in \mathbb{R}^n , and let \hat{y} be the orthogonal projection of y onto W. Then \hat{y} is the closest point in W to y, in the sense that $||y - \hat{y}|| < ||y - v||$ for all v in W distinct from \hat{y} .

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- The vector \hat{y} in Theorem 9 is called the best approximation to y by elements of W.

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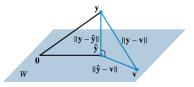
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- Inequality $||y \hat{y}|| < ||y v||$ leads to a new proof that \hat{y} does not depend on the particular orthogonal basis used to compute it.
- If a different orthogonal basis for W were used to construct an orthogonal projection of y, then this projection would also be the closest point in W to y, namely, \hat{y} .

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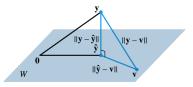
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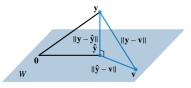


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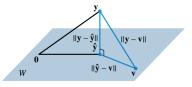
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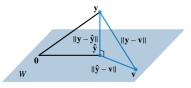
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- Now $||\hat{y} v||^2 > 0$ because $\hat{y} v \neq 0$, and so inequality follows immediately.

• The distance from a point y in **R**ⁿ to a subspace W is defined as the distance from y to the nearest point in W.

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• So
$$\hat{y} = \frac{15}{30}u_1 + \frac{-21}{6}u_2 = \begin{bmatrix} -1\\ -8\\ 4 \end{bmatrix}$$

 $\hat{y} = \frac{\hat{y} \cdot \hat{u}}{\hat{u}_1 \hat{u}_1} \hat{u}_1 + \frac{\hat{y} \cdot \hat{u}_2}{\hat{u}_2 \hat{u}_2} \hat{u}_2$

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• Theorem 10. If $\{u_1, \ldots, u_p\}$ is an orthogonormal basis for a subspace W of \mathbb{R}^n , then

$$proj_W y = (y \cdot u_1)u_1 + (y \cdot u_2)u_2 + \ldots + (y \cdot u_p)u_p$$

If
$$U = [u_1 \ u_2 \ \dots \ u_p]$$
, then $proj_W y = UU^T y$ for all $y \in \mathbf{R}^n$.

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